#### Lecture #8

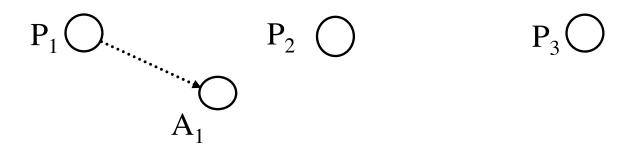
- Multiparent create
- Expressive power
- Typed Access Control Matrix (TAM)
- Overview of Policies
- The nature of policies
  - What they cover

## Expressiveness

- Graph-based representation to compare models
- Graph
  - Vertex: represents entity, has static type
  - Edge: represents right, has static type
- Graph rewriting rules:
  - Initial state operations create graph in a particular state
  - Node creation operations add nodes, incoming edges
  - Edge adding operations add new edges between existing vertices

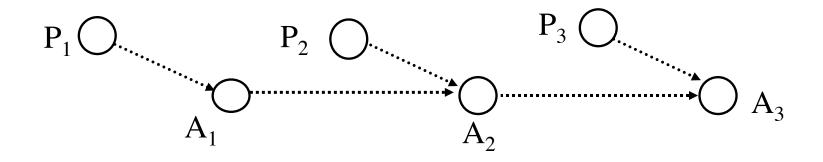
### Example: 3-Parent Joint Creation

- Simulate with 2-parent
  - Nodes  $\mathbf{P}_1, \mathbf{P}_2, \mathbf{P}_3$  parents
  - Create node C with type c with edges of type e
  - Add node  $\mathbf{A}_1$  of type *a* and edge from  $\mathbf{P}_1$  to  $\mathbf{A}_1$  of type e'



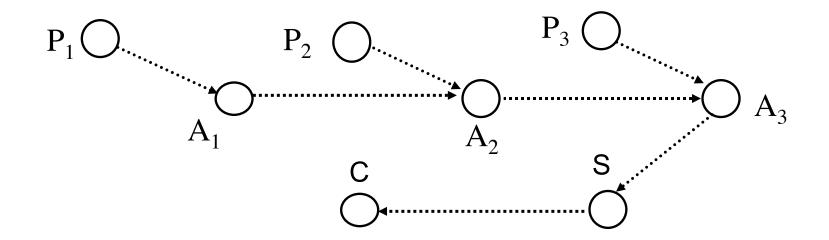
### Next Step

- $\mathbf{A}_1, \mathbf{P}_2$  create  $\mathbf{A}_2; \mathbf{A}_2, \mathbf{P}_3$  create  $\mathbf{A}_3$
- Type of nodes, edges are a and e'

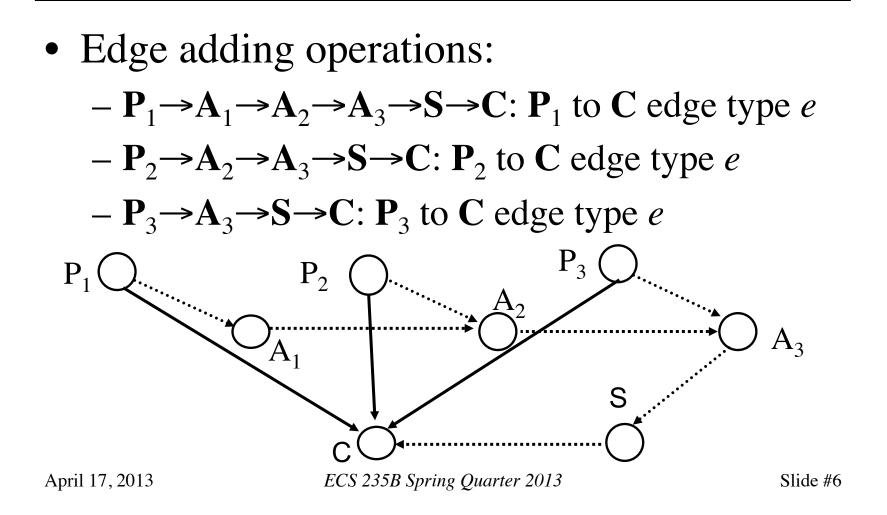


#### Next Step

- A<sub>3</sub> creates **S**, of type *a*
- S creates C, of type c



### Last Step



### Definitions

- *Scheme*: graph representation as above
- *Model*: set of schemes
- Schemes *A*, *B correspond* if graph for both is identical when all nodes with types not in *A* and edges with types in *A* are deleted

# Example

- Above 2-parent joint creation simulation in scheme *TWO*
- Equivalent to 3-parent joint creation scheme *THREE* in which P<sub>1</sub>, P<sub>2</sub>, P<sub>3</sub>, C are of same type as in *TWO*, and edges from P<sub>1</sub>, P<sub>2</sub>, P<sub>3</sub> to C are of type *e*, and no types *a* and *e* exist in *TWO*

### Simulation

Scheme A simulates scheme B iff

- every state *B* can reach has a corresponding state in *A* that *A* can reach; and
- every state that *A* can reach either corresponds to a state *B* can reach, or has a successor state that corresponds to a state *B* can reach
  - The last means that A can have intermediate states not corresponding to states in B, like the intermediate ones in TWO in the simulation of THREE

## Expressive Power

- If there is a scheme in *MA* that no scheme in *MB* can simulate, *MB* less expressive than *MA*
- If every scheme in *MA* can be simulated by a scheme in *MB*, *MB* as expressive as *MA*
- If *MA* as expressive as *MB* and *vice versa*, *MA* and *MB* equivalent

# Example

- Scheme A in model M
  - Nodes  $\mathbf{X}_1, \mathbf{X}_2, \mathbf{X}_3$
  - 2-parent joint create
  - 1 node type, 1 edge type
  - No edge adding operations
  - Initial state:  $\mathbf{X}_1, \mathbf{X}_2, \mathbf{X}_3$ , no edges
- Scheme *B* in model *N* 
  - All same as A except no 2-parent joint create
  - 1-parent create
- Which is more expressive?

### Can *A* Simulate *B*?

- Scheme *A* simulates 1-parent create: have both parents be same node
  - Model *M* as expressive as model *N*

### Can *B* Simulate *A*?

- Suppose X<sub>1</sub>, X<sub>2</sub> jointly create Y in A
  Edges from X<sub>1</sub>, X<sub>2</sub> to Y, no edge from X<sub>3</sub> to Y
- Can *B* simulate this?
  - Without loss of generality,  $\mathbf{X}_1$  creates  $\mathbf{Y}$
  - Must have edge adding operation to add edge from  $\mathbf{X}_2$  to  $\mathbf{Y}$
  - One type of node, one type of edge, so operation can add edge between any 2 nodes

## No

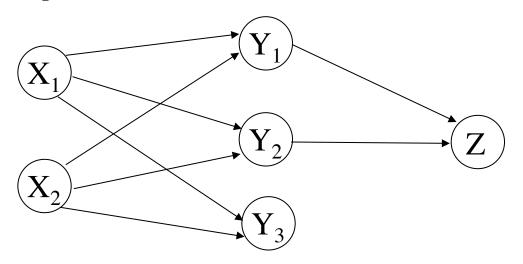
- All nodes in *A* have even number of incoming edges
  - 2-parent create adds 2 incoming edges
- Edge adding operation in *B* that can edge from  $X_2$  to C can add one from  $X_3$  to C
  - A cannot enter this state
    - *A*, cannot have node (**C**) with 3 incoming edges
  - B cannot transition to a state in which Y has even number of incoming edges
    - No remove rule
- So *B* cannot simulate *A*; *N* less expressive than *M* April 17, 2013 *ECS 235B Spring Quarter 2013* Slide #14

#### Theorem

- Monotonic single-parent models are less expressive than monotonic multiparent models
- Proof by contradiction
  - Scheme *A* is multiparent model
  - Scheme *B* is single parent create
  - Claim: *B* can simulate *A*, without assumption that they start in the same initial state
    - Note: example assumed same initial state

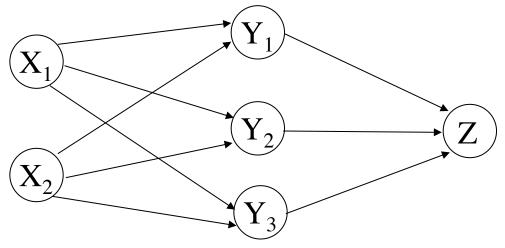
#### Outline of Proof

- $\mathbf{X}_1, \mathbf{X}_2$  nodes in A
  - They create  $\mathbf{Y}_1, \mathbf{Y}_2, \mathbf{Y}_3$  using multiparent create rule
  - $\mathbf{Y}_1$ ,  $\mathbf{Y}_2$  create  $\mathbf{Z}$ , again using multiparent create rule
  - *Note*: no edge from  $\mathbf{Y}_3$  to  $\mathbf{Z}$  can be added, as A has no edge-adding operation



#### Outline of Proof

- $\mathbf{W}, \mathbf{X}_1, \mathbf{X}_2$  nodes in *B* 
  - W creates  $\mathbf{Y}_1, \mathbf{Y}_2, \mathbf{Y}_3$  using single parent create rule, and adds edges for  $\mathbf{X}_1, \mathbf{X}_2$  to all using edge adding rule
  - $\mathbf{Y}_1$  creates  $\mathbf{Z}$ , again using single parent create rule; now must add edge from  $\mathbf{X}_2$  to  $\mathbf{Z}$  to simulate A
  - Use same edge adding rule to add edge from  $\mathbf{Y}_3$  to  $\mathbf{Z}$ : cannot duplicate this in scheme *A*!



April 17, 2013

# Meaning

- Scheme *B* cannot simulate scheme *A*, contradicting hypothesis
- ESPM more expressive than SPM
  - ESPM multiparent and monotonic
  - SPM monotonic but single parent

# Typed Access Matrix Model

- Like ACM, but with set of types *T* 
  - All subjects, objects have types
  - Set of types for subjects TS
- Protection state is  $(S, O, \tau, A)$ 
  - $-\tau: O \rightarrow T$  specifies type of each object
  - If **X** subject,  $\tau(\mathbf{X}) \in TS$
  - If **X** object,  $\tau(\mathbf{X}) \in T TS$

### Create Rules

- Subject creation
  - create subject s of type ts
  - s must not exist as subject or object when operation executed
  - $-ts \in TS$
- Object creation
  - create object *o* of type *to*
  - *o* must not exist as subject or object when operation executed
  - $-to \in T TS$

#### Create Subject

- Precondition:  $s \notin S$
- Primitive command: create subject s of type t
- Postconditions:

$$-S' = S \cup \{s\}, O' = O \cup \{s\}$$
  
-  $(\forall y \in O)[\tau'(y) = \tau(y)], \tau'(s) = t$   
-  $(\forall y \in O')[a'[s, y] = \emptyset], (\forall x \in S')[a'[x, s] = \emptyset]$   
-  $(\forall x \in S)(\forall y \in O)[a'[x, y] = a[x, y]]$ 

### Create Object

- Precondition:  $o \notin O$
- Primitive command: create object *o* of type *t*
- Postconditions:

$$-S' = S, O' = O \cup \{ o \}$$
  
-  $(\forall y \in O)[\tau'(y) = \tau(y)], \tau'(o) = t$   
-  $(\forall x \in S')[a'[x, o] = \emptyset]$   
-  $(\forall x \in S)(\forall y \in O)[a'[x, y] = a[x, y]]$ 

### Definitions

• MTAM Model: TAM model without **delete**, **destroy** 

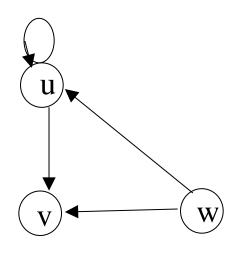
– MTAM is Monotonic TAM

- $\alpha(x_1:t_1, ..., x_n:t_n)$  create command
  - $t_i$  child type in  $\alpha$  if any of create subject  $x_i$  of type  $t_i$  or create object  $x_i$  of type  $t_i$  occur in  $\alpha$
  - $-t_i$  parent type otherwise

### Cyclic Creates

```
command havoc(s : u, p : u, f : v, q : w)
create subject p of type u;
create object f of type v;
enter own into a[s, p];
enter r into a[q, p];
enter own into a[p, f];
enter r into a[p, f]
end
```

### Creation Graph

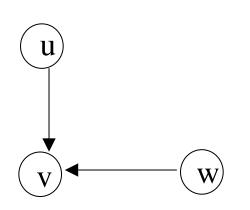


- *u*, *v* child types
- *u*, *w* parent types
- Graph: lines from parent types to child types
- This one has cycles

### Acyclic Creates

```
command havoc(s : u, p : u, f : v, q : w)
    create object f of type v;
    enter own into a[s, p];
    enter r into a[q, p];
    enter own into a[p, f];
    enter r into a[p, f]
end
```

### Creation Graph



- *v* child type
- *u*, *w* parent types
- Graph: lines from parent types to child types
- This one has no cycles

#### Theorems

• Safety decidable for systems with acyclic MTAM schemes

– In fact, it's NP-hard

- Safety for acyclic ternary MATM decidable in time polynomial in the size of initial ACM
  - "Ternary" means commands have no more than 3 parameters
  - Equivalent in expressive power to MTAM

# **Comparing Security Properties**

- Generalize what we have done earlier
  - Property we looked at is safety question
  - Others of interest are bounds on determining safety, what actions a specific subject can take, etc.
- Also eliminate the requirement of monotonicity
- Key idea: access requests are queries

### Scheme (Alternate Definition)

- $\Sigma$  set of states
- Q set of querties
- $e: \Sigma \times Q \rightarrow \{ \text{ true, false } \} (entailment relation})$
- T set of transition rules

Access control scheme is  $(\Sigma, Q, e, T)$ 

#### Note

- We write  $\sigma \vdash_{\tau} \sigma'$  for  $\tau$  changing the system from state  $\sigma$  to state  $\sigma'$
- We write  $\sigma \mapsto_{\tau} \sigma'$  for  $\tau$  allowing the system to change from state  $\sigma$  to state  $\sigma'$

It doesn't actually change the state

## Example: Take-Grant

- $\Sigma$  set of all possible protection graphs
- Q set of queries {  $can \bullet share(\alpha, \mathbf{v}_1, \mathbf{v}_2, G_0)$  }
- $e: e(\sigma_0, q) = true \text{ if } q \text{ holds; false if not}$
- T set of sequences of take, grant, create, remove rules
- So take-grant is an access control scheme

## Security Analysis Instance

- $(\Sigma, Q, e, T)$  access control scheme
- Security analysis instance is  $(\sigma, q, \tau, \Pi)$  where:  $-\sigma \in \Sigma, q \in Q, \tau \in T$ 
  - $-\Pi$  is  $\forall$  or  $\exists$
- $\Pi$  is  $\exists$ : does there exist a state  $\sigma'$  such that  $\sigma$  $\mapsto^* \sigma'$  and  $e(\sigma', q) =$  true
- $\Pi$  is  $\forall$ : for all states  $\sigma'$  such that  $\sigma \mapsto^* \sigma'$ , is  $e(\sigma', q) = \text{true}$

# Multiple Queries

- $(\Sigma, Q, e, T)$  access control scheme
- Compositional security analysis instance is (σ, φ, τ, Π) where φ is a propositional logic formula of queries from Q

# Mapping from *A* to *B*

- A mapping from  $A = (\Sigma^A, Q^A, e^A, T^A)$  to  $B = (\Sigma^B, Q^B, e^B, T^B)$  is a function  $f: (\Sigma^A \times T^A) \cup Q^A (\Sigma^B \times T^B) \cup Q^B$
- Idea:
  - Each query in A corresponds to one in B
  - Each state, transition pair in A corresponds to a pair in B

## Security-Preserving Mappings

- $f: A \to B$
- Image of a security analysis instance ( $\sigma^A$ ,  $q^A$ ,  $\tau^A$ ,  $\Pi$ ) under f is ( $\sigma^B$ ,  $q^B$ ,  $\tau^B$ ,  $\Pi$ ), where:  $-f((\sigma^A, \tau^A)) = (\sigma^B, \tau^B)$  and  $f(q^A) = q^B$
- *f* is *security-preserving* if every security analysis instance in *A* is true iff its image in *B* is true

### Strongly Security-Preserving

- Like security-preserving, but for compositional security analyses instances
- That is, for the image, instead of  $f(q^A) = q^B$ we have  $f(\mathbf{\Phi}^A) = \mathbf{\Phi}^B$

## Two Mapped Models

- Consider access control schemes A and B with a mapping  $f: A \rightarrow B$
- Security properties deal with answers to queries about states and transitions
- Given 2 corresponding states and 2 corresponding sequences of transitions, corresponding queries must give same answer!

#### Equivalent Under Mapping

- $A = (\Sigma^A, Q^A, e^A, T^A)$
- $B = (\Sigma^B, Q^B, e^B, T^B)$
- $f: A \rightarrow B$
- $\sigma^A$ ,  $\sigma^B$  equivalent under mapping f when  $e^A(\sigma^A, q^A) = e^B(\sigma^B, q^B)$

#### State-Matching Reduction

- *f* is *state-matching reduction* if, for every  $\sigma^A \in \Sigma^A$  and  $\tau^A \in T^A$ ,  $(\sigma^B, \tau^B) = f((\sigma^A, \tau^A))$  has the following properties:
  - $\forall (\sigma'^A \in \Sigma^A)$  such that  $\sigma^A \mapsto_{\tau}^* \sigma'^A$ , there is a state  $\sigma'^B \in \Sigma^B$  such that  $\sigma^B \mapsto_{\tau}^* \sigma'^B$ , and  $\sigma'^A$  and  $\sigma'^B$  are equivalent under the mapping *f*
  - $\forall (\sigma' {}^{B} \in \Sigma^{B})$  such that  $\sigma^{B} \mapsto_{\tau}^{*} \sigma' {}^{B}$ , there is a state  $\sigma' {}^{A} \in \Sigma^{A}$  such that  $\sigma^{A} \mapsto_{\tau}^{*} \sigma' {}^{A}$ , and  $\sigma' {}^{A}$  and  $\sigma' {}^{B}$  are equivalent under the mapping *f*

April 17, 2013

ECS 235B Spring Quarter 2013

#### Theorem

• A mapping  $f: A \rightarrow B$  is strongly securitypreserving iff f is a state-matching reduction

## Expressive Power

If access control model *MA* has a scheme that cannot be mapped into a scheme in access control model *MB* using a state-matching reduction, then model *MB* is *less expressive than* model MA. If every scheme in model *MA* can be mapped into a scheme in model *MB* using a state-matching reduction, then model *MB* is *as expressive as* model *MA*. If *MA* is as expressive as *MB*, and *MB* is as expressive as *MA*, the models are *equivalent*.

• Note it does not require schemes to be monotonic!

## Security Policies

- Overview
- The nature of policies
  - What they cover
  - Policy languages
- The nature of mechanisms
  - Types
  - Secure vs. precise
- Underlying both
  - Trust

#### Overview

- Policies
- Trust
- Nature of Security Mechanisms
- Policy Expression Languages
- Limits on Secure and Precise Mechanisms

# Security Policy

- Policy partitions system states into:
  - Authorized (secure)
    - These are states the system can enter
  - Unauthorized (nonsecure)
    - If the system enters any of these states, it's a security violation
- Secure system
  - Starts in authorized state
  - Never enters unauthorized state

#### Confidentiality

- X set of entities, I information
- *I* has *confidentiality* property with respect to *X* if no  $x \in X$  can obtain information from *I*
- *I* can be disclosed to others
- Example:
  - *X* set of students
  - *I* final exam answer key
  - *I* is confidential with respect to *X* if students cannot obtain final exam answer key

# Integrity

- X set of entities, I information
- *I* has *integrity* property with respect to *X* if all *x* ∈ *X* trust information in *I*
- Types of integrity:
  - trust *I*, its conveyance and protection (data integrity)
  - *I* information about origin of something or an identity (origin integrity, authentication)
  - *I* resource: means resource functions as it should (assurance)

### Availability

- X set of entities, I resource
- *I* has *availability* property with respect to *X* if all  $x \in X$  can access *I*
- Types of availability:
  - traditional: *x* gets access or not
  - quality of service: promised a level of access (for example, a specific level of bandwidth) and not meet it, even though some access is achieved

# Policy Models

- Abstract description of a policy or class of policies
- Focus on points of interest in policies
  - Security levels in multilevel security models
  - Separation of duty in Clark-Wilson model
  - Conflict of interest in Chinese Wall model

# Types of Security Policies

- Military (governmental) security policy
   Policy primarily protecting confidentiality
- Commercial security policy
  - Policy primarily protecting integrity
- Confidentiality policy
  - Policy protecting only confidentiality
- Integrity policy
  - Policy protecting only integrity

# Integrity and Transactions

- Begin in consistent state
  - "Consistent" defined by specification
- Perform series of actions (*transaction*)
  - Actions cannot be interrupted
  - If actions complete, system in consistent state
  - If actions do not complete, system reverts to beginning (consistent) state

#### Trust

Administrator installs patch

- 1. Trusts patch came from vendor, not tampered with in transit
- 2. Trusts vendor tested patch thoroughly
- 3. Trusts vendor's test environment corresponds to local environment
- 4. Trusts patch is installed correctly

### Trust in Formal Verification

- Gives formal mathematical proof that given input *i*, program *P* produces output *o* as specified
- Suppose a security-related program *S* formally verified to work with operating system *O*
- What are the assumptions?